



Defect Identification with Predictive Maintenance for Enhanced Photovoltaic System Performance

Eman Ashraf¹, A.R. Habieeb^{2,3}, Kabeel A. E.^{2,4}, Warda M. Shaban⁴

¹ Dept. of Electronics and Communications Engineering, Faculty of Engineering, Delta University for Science and Technology, Gamasa, Egypt, <https://orcid.org/0000-0003-0928-3580>, Eman.ashraf@deltauniv.edu.eg

² Faculty of Engineering, Delta University for Science and Technology, Gamasa, Egypt, abedrabiee@gmail.com

³ Mechatronics Engineering Program, Faculty of Engineering, Mansura University, Mansura, Egypt

⁴ Mechanical Power Engineering Department, Tanta University, Tanta, Egypt, kabeel6@f-eng.tanta.edu.eg

⁵ dept. of Communications and Electronics Engineering, Nile Higher Institute for Engineering and Technology, Artificial Intelligence Lab, Mansoura, Egypt, warda_mohammed@nilehi.edu.eg

Correspondence: Eman Ashraf; Tel 01003013758, Email : Eman.ashraf@deltauniv.edu.eg

ABSTRACT

This research paper addresses the critical challenge of ensuring the optimal performance and longevity of photovoltaic (PV) systems through defect detection and maintenance prediction. PV cells play a pivotal role in renewable energy generation, and their efficiency can be compromised by defects. This study presents a novel approach that combines Deep Learning (DL) techniques for defect detection and Machine Learning (ML) models for maintenance prediction. The proposed Convolutional Neural Network (CNN) architecture accurately detects defects in PV cell images, achieving high precision, recall, and F1-score. Furthermore, a separate maintenance prediction model, based on extracted features from the defect detection model, effectively predicts the maintenance requirements of PV cells. The integration of these models provides a comprehensive solution for identifying defects and anticipating maintenance needs in PV systems, contributing to the sustainability and reliability of renewable energy sources. The developed defect detection model achieves exceptional accuracy and precision in identifying defects, while the predictive maintenance model enhances the reliability and cost-effectiveness of maintenance operations.

Keywords: Photovoltaic, Maintenance, Defect Detection, Machine Learning, Deep Learning

1. Introduction

PV cells, also known as solar cells, form the cornerstone of renewable energy generation by harnessing the power of sunlight to convert it into electricity. In an era marked by escalating concerns over climate change and diminishing fossil fuel resources, the significance of PV cells in driving sustainable energy solutions has become increasingly pronounced. PV technology offers a cleaner and more environmentally friendly alternative to traditional energy sources, presenting a pivotal opportunity to mitigate greenhouse gas emissions and reduce dependence on finite fossil fuels[1].

The demand for electricity is consistently rising due to global industrialization and the proliferation of electronic devices. However, this surge in demand has underscored the need for energy sources that can provide reliable and continuous power supply without exacerbating environmental degradation. PV cells exhibit this dual capability offering both a sustainable energy solution and a mechanism for reducing the carbon footprint of energy production[2].

As governments, industries, and individuals worldwide intensify their commitment to combatting climate change and transitioning to sustainable energy systems, the role of PV cells has evolved from a niche technology to a central pillar of the renewable energy landscape. This paper delves into a crucial aspect of PV cells' functionality—detecting defects and predicting maintenance needs—to ensure the continued efficiency and longevity of these essential components in the pursuit of a greener and more sustainable future[3].

PV cells represent a groundbreaking innovation in renewable energy generation, converting sunlight directly into electricity. In an era characterized by mounting concerns over climate change and the depletion of conventional energy resources, the role of PV cells in providing a clean and sustainable energy source has become paramount.

These cells offer a viable solution to meet the escalating energy demands of modern society while minimizing the ecological footprint associated with traditional energy production methods[4].

The seamless functioning of PV systems is crucial for maximizing energy output and ensuring a robust return on investment. However, the efficiency and longevity of PV systems can be jeopardized by various factors, with defects in PV cells being a primary concern. Defects, whether they stem from manufacturing imperfections, environmental stressors, or wear over time, can hinder energy production, leading to suboptimal performance and reduced overall system efficiency. Identifying and rectifying these defects in a timely manner is essential to maintain the energy yield and financial viability of PV installations[5].

Predictive maintenance emerges as a key strategy to address this challenge. By anticipating maintenance needs based on the degradation patterns of PV cells, operators can strategically plan interventions, thereby minimizing downtime and optimizing system efficiency. Predictive maintenance also contributes to extending the operational lifespan of PV systems, ultimately enhancing their return on investment and reducing the need for premature replacements.

This research paper aims to tackle the pivotal issues of defect detection and predictive maintenance in PV systems through the innovative application of ML techniques[6]. The primary objectives of this study are:

- Defect Detection: Develop a robust DL model capable of accurately identifying defects in PV cell images. This model will leverage CNNs to achieve high precision and recall in defect classification.
- Predictive Maintenance: Establish a predictive maintenance model that utilizes the features extracted from the defect detection model to anticipate maintenance needs in PV cells. This model will aid in strategically planning maintenance actions to ensure continuous and efficient energy production.

The research outcomes hold significant practical implications for the renewable energy sector, providing a foundation for the development of intelligent PV systems that optimize energy production, reduce downtime, and contribute to the global transition towards sustainable energy sources.

In conclusion, this paper sets out to advance the field of PV system management by addressing the critical challenges of defect detection and predictive maintenance, aligning with the overarching goals of enhancing energy efficiency and fostering the sustainable growth of renewable energy technologies.

2. Related work

The CNN was utilized by Zyout and Qataweh to analyze the surface of the PV panel and identify any potential defects. The utilization of transfer learning using the AlexNet CNN exhibited highly encouraging results and demonstrated the potential of this approach for detecting diverse flaws on the surface of solar panels. The acquired results demonstrate promise and highlight the potential of CNNs in the development of computer vision applications. This potential extends beyond the mere provision of high-quality and large-scale manufacture of solar panels, encompassing the areas of maintenance and sustainability of solar energy systems as well[7].

Venkatesh and Sugumaran use unmanned aerial vehicle photos to detect PV module PVM faults using DL. The softmax activation function is used to classify images and extract high-level features using CNNs. Pre-trained Visual Geometry Group (VGG-16) networks extract features and classify faults. The study considers six test circumstances. Test circumstances include burn marks, delamination, discoloration, glass breakage, excellent panels, and snail trails [8].

To identify PV module faults, Wang et al. devised a hybrid approach that combines the symmetrized dot pattern (SDP) with a CNN. The failure of bypass diodes, inadequate welding, and fracture are three common defects that are described. In addition, the experiment included a fault-free module for comparison. The high-speed data acquisition (DAQ) card NI PXI-5105 was used to collect the original signal after first importing a high-frequency square signal into the PV module for the hardware architecture. The signal was then fed into the SDP, where it was processed to produce a snowflake image that served as the image feature for problem diagnostics. Finally, CNN was used to identify faults in PV modules. In this investigation, there were 3200 test data records; 800 test data records (200 records for each defect) served as test samples. The test results demonstrate a 99.88% recognition accuracy rate. With a 91.75% accuracy rate, it outperforms the conventional ENN method. As a result, the suggested method successfully detects the fault kinds in the PV modules while successfully capturing the failure signals and visualizing them in photos[9].

By combining CNN and the Wasserstein generative adversarial network (WGAN) data augmentation technology, Xiaoyang et al. devised a fault diagnosis method. The suggested discriminator and generator can both learn the

distribution of PV array fault signal and noise brought on by environmental factors through adversarial training. The well-trained generator then creates a large number of fictitious data samples to give a helpful gradient for additional CNN classifier training. Additionally, all of the created and gathered Electrical time series graph (ETSG) samples are utilized to train a CNN classifier to precisely identify PV array problems, such as Line-line faults (LLF) with various mismatch levels and Open-circuit faults (OCF) with various mismatch levels[10].

Ghada et al. increased the PV array system fault diagnosis convergence and forecast accuracy. This method operates by combining the classification and prediction capabilities of DL with the ability of particle swarm optimization (PSO) to locate the optimal answer in the search space. From the PV array's output, a few parameters are taken out to be utilized as identification tools for the system's fault diagnostics. Results obtained with the backpropagation (BP) neural network approach alone and those obtained with the BP heuristic combination method are compared. The suggested BP-PSO algorithm only converges after 250 steps in the training phase, whereas the BP algorithm converges after 350 steps. The suggested BP-PSO method obtained 95% of correct predictions, compared to the BP algorithms' accuracy of roughly 87.8%. The convergence of the simulation as well as the precision of the forecast of the fault diagnosis in the PV system were improved by the findings of the BP heuristic combination technique[11].

To solve the issue of failure diagnosis of PV modules using thermographic images, Kellil et al. looked at a CNN model and a fine-tuned model based on (VGG-16). We have employed binary classification and multiclass classification for fault detection. The database that was employed in this investigation consisted of an unbalanced class distribution of infrared thermographic images of PV modules under both normal and defective conditions (such as bypass diode failure, a partially covered PV module, shading effect, short-circuit, and dust deposit on the PV surface). In the north of Algeria, the Unit for Developing Solar Equipment (UDES), is where the test site is situated. For the five different types of defects, the average accuracy archived using the improved VGG-16 model is 99.91% for fault detection and 99.80% for fault diagnosis. According to experimental studies, the fine-tuned model produces highly accurate prediction results, whereas the small Deep Convolutional Neural Network (small-DCNN) model produces somewhat less accuracy[12].

A brand-new hybrid model was created by Benghanem et al. for PV module defect diagnostics. The ML algorithm and CNN are combined in the model. In this study, seven faults were taken into account: sand buildup on PV modules, PV modules that were covered, PV modules that were cracked, degradation, filthy PV modules, short-circuited PV modules, and overheated bypass diodes. First, a hybrid CNN-ML system has been created to categorize the seven most frequent problems found in PV modules. After that, the developed model was optimized. Third, a microprocessor (Raspberry Pi 4) has the optimized model built into it for real-time use. To enable users, to analyze their PV modules, a user-friendly graphical user interface (GUI) has finally been created. An enormous database compiled from three regions with various climatic conditions (Mediterranean, arid, and semi-arid climates) was used to assess the suggested hybrid model. The viability of such an embedded approach in the diagnostics of PV modules was demonstrated by experimental experiments. In this research, a comparison between our model and the most recent models is also discussed[13].

3. Background

3.1 Convolutional Neural Networks (CNNs)

CNN have revolutionized the field of computer vision and pattern recognition. They are a class of deep neural networks designed to process grid-like data, such as images and videos. CNNs have achieved remarkable success in various applications, from image classification to object detection, and have become a fundamental tool in modern ML. This article provides a detailed overview of CNNs, including their architecture, components, training process, and applications.

A CNN architecture, as shown in Fig. 1, is specifically designed to capture the spatial hierarchies and patterns present in visual data. It consists of several layers that gradually learn higher-level features from raw pixel values. The primary components of a CNN include:

- **Convolutional Layer:** This layer applies filters (also known as kernels) to the input image, detecting specific features such as edges, corners, or textures. The convolution operation involves element-wise multiplication of the filter with local regions of the input, followed by summation.
- **Activation Function:** Commonly used activation functions like ReLU (Rectified Linear Unit) introduce non-linearity to the network, enabling it to learn complex patterns.
- **Pooling Layer:** Pooling layers reduce spatial dimensions, making the network more computationally efficient and robust to small variations. Max pooling and average pooling are widely used techniques.
- **Fully Connected Layer:** The final layers of the network are fully connected, performing high-level feature extraction and classification.

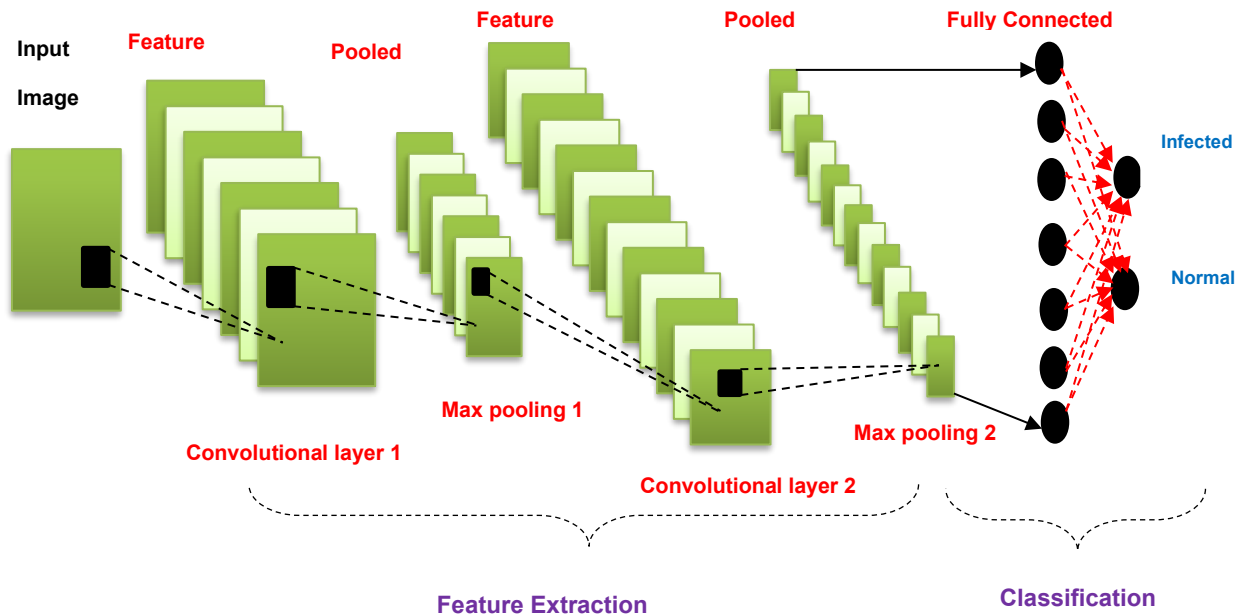


Fig. 1. The architecture structure of CNN

3.2 Genetic algorithm:

A Genetic Algorithm (GA) represents a powerful and versatile optimization technique inspired by the process of natural selection and genetics. Rooted in evolutionary biology, a GA iteratively evolves a population of potential solutions to a problem, aiming to discover the best solution over successive generations. This algorithmic approach employs genetic operators like selection, crossover, and mutation to mimic the processes of inheritance, recombination, and mutation observed in biological evolution, as shown in Algorithm 1. GAs are particularly valuable for solving complex problems where an exhaustive search would be impractical due to the immense solution space. By exploring diverse solution candidates, GAs can efficiently navigate towards optimal or near-optimal solutions. Their adaptability and versatility make them applicable across various domains, from engineering and economics to artificial intelligence and bioinformatics. GAs continue to be a foundational tool in optimization, providing an elegant and effective means to tackle intricate challenges and uncover solutions that might otherwise remain hidden in the complexity of the problem landscape.

Algorithm 1: Genetic Algorithm

```

1:  function GeneticAlgorithm():
2:      Initialize population

3:      Evaluate fitness of each individual
4:      Replace old population with new offspring
5:      return best individual
6:  function InitializePopulation():
7:      population = []
8:      for _ in range(population_size):
9:          individual = create_random_individual()
10:         population.append(individual)
11:     return population
12:  function Selection(population):
13:     selected_parents = []
14:     for _ in range(num_parents):
15:         parent = select_one_individual(population)

        # E.g., tournament selection
16:         selected_parents.append(parent)
17:     return selected_parents
18:  function Crossover(parent1, parent2):
19:     point = random_point() # Determine crossover point
20:     child1 = parent1[:point] + parent2[point:]
21:     child2 = parent2[:point] + parent1[point:]
22:     return child1, child2
23:  function Mutation(individual):
24:     mutated_individual = individual.copy()
25:     for gene in mutated_individual:
26:         if random() < mutation_rate:
27:             mutate(gene)
28:     return mutated_individual
29:  # Main process

    best_solution = GeneticAlgorithm()

```

4. Proposed algorithm**4.1 Proposed CNN-GA for Defect Detection, Localization, and Classification**

The proposed system integrates a CNN with a GA to optimize the hyperparameters of the CNN architecture, leading to enhanced performance in various computer vision tasks. This innovative approach harnesses the power of DL and evolutionary optimization to automatically discover the most effective combination of hyperparameters that best suit the dataset and task at hand. By employing the GA, the system efficiently explores a broad search space of possible hyperparameter configurations, iteratively improving the CNN's architecture for optimal results. This amalgamation of advanced techniques not only minimizes manual trial-and-error but also boosts the network's ability to capture intricate features in images.

The proposed methodology encompasses training the CNN with the optimized architecture achieved through the GA, as shown in Algorithm 2. By combining this specialized preprocessing technique with a tailored architecture, the network becomes adept at detecting and categorizing defects in diverse materials or structures. The filters highlights edges and boundaries, enhancing the network's sensitivity to defect-specific features.

Moreover, the dataset is meticulously labeled, encompassing an array of defects such as Hotspots, Micro cracks, Erosion, and Dust deposition. This comprehensive annotation strategy empowers the CNN to differentiate and accurately classify these distinct defect types, ensuring the system's precision and applicability across a wide range of scenarios.

The methodology goes a step further by enabling the localization of defects through the examination of the CNN's feature maps. By analyzing the activated regions within these maps, the network can precisely pinpoint the locations in the input image corresponding to various defect types. This localization capability not only enriches the system's interpretability but also equips engineers and analysts with invaluable information regarding the precise nature and whereabouts of detected defects.

In essence, the proposed approach harnesses the power of optimized CNN architecture to achieve effective defect detection and classification. The added ability to localize defects using feature map analysis solidifies the methodology's utility for applications such as quality assurance in manufacturing and structural integrity assessment.

Algorithm 2: proposed optimized CNN with GA

```

1:  function evaluate_fitness(individual):
2:    # Build CNN model with hyperparameters from individual

    model = build_cnn_model(individual)
3:    # Train and evaluate the model

    accuracy = train_and_evaluate_model(model)
4:    return accuracy
5:  function initialize_population(pop_size):
6:    population = []
7:    for _ in range(pop_size):
8:      individual = create_random_individual()
9:      population.append(individual)
10:   return population
11:  function select_parents(population):
12:    parents = []
13:    for _ in range(num_parents):
14:      parent = select_one_individual(population)

      # E.g., using tournament selection
15:      parents.append(parent)
16:   return parents
17:  function crossover(parent1, parent2):
18:    # Create a copy of parent1

    child1 = parent1.copy()
19:    # Create a copy of parent2

    child2 = parent2.copy()
21:    # Apply crossover operation on child1 and child2

    return child1, child2
22:  function mutate(individual):
23:    # Create a copy of the original individual

    mutated_individual = individual.copy()
25:    # Apply mutation operation on mutated_individual

```

```

    return mutated_individual
26:  function genetic_algorithm(pop_size, num_generations):
27:      population = initialize_population(pop_size)
28:      for generation in range(num_generations):
30:          # Evaluate fitness for each individual

          for individual in population:
31:              individual.fitness = evaluate_fitness(individual)
32:              # Select parents for reproduction

          parents = select_parents(population)
34:          # Create offspring through crossover and mutation

          offspring = []
35:          while len(offspring) < pop_size - len(parents):
36:              parent1, parent2 = select_two_parents(parents)
37:              child1, child2 = crossover(parent1, parent2)
38:              offspring.extend([child1, child2])
40:              # Apply mutation to offspring

          for individual in offspring:
41:              if random() < mutation_rate:
42:                  individual = mutate(individual)
43:              # Replace old population with new offspring

          population = parents + offspring
44:          # Select the best individual from the final population

          best_individual = select_best_individual(population)
45:          return best_individual

```

4.2 Maintenance Prediction Model

The proposed Maintenance Prediction Model capitalizes on the previously localized defect regions from the defect detection process. This approach leverages the insights gained from defect analysis and serves as a valuable step towards predictive maintenance strategies. The procedure involves extracting intricate defect features from the localized regions, employing these features as input for a predictive maintenance model.

To execute this, localized defect regions' distinctive attributes are meticulously captured. These attributes encapsulate critical information about the type, size, and severity of defects. The localized defect features are then utilized as inputs for a specialized maintenance prediction model. This model uses Support Vector Machine (SVM), renowned for its efficacy in classification tasks and predictive modeling, as shown in Algorithm 3.

Subsequently, the maintenance prediction model is trained to harness the relationship between extracted defect features and maintenance requirements. By learning from historical data that correlates defects with subsequent maintenance actions, the model becomes proficient in forecasting maintenance needs based on the identified defect patterns.

In essence, the Maintenance Prediction Model harmonizes defect analysis with predictive modeling to provide informed insights into future maintenance demands. This strategic amalgamation not only enhances asset

management but also contributes to cost reduction and operational efficiency. As the system learns and evolves, it empowers decision-makers with actionable intelligence for optimal maintenance planning and resource allocation.

Algorithm 3: maintenance prediction model

```

1:  function MaintenancePredictionModel(defect_features, maintenance_data):
2:    # Train the maintenance prediction model

        model = train_maintenance_model(defect_features, maintenance_data)
3:    return model
4:  function TrainMaintenanceModel(defect_features, maintenance_data):
5:    # Prepare training data

        X_train = defect_features

        y_train = maintenance_data
6:    # Initialize and train the maintenance prediction model (SVM)

        model = initialize_model()
7:    model.train(X_train, y_train)
8:    return model
9:    # Main process

        defect_features = extract_defect_features(localized_defect_regions)
10:   maintenance_data = load_maintenance_data()
11:   maintenance_model = MaintenancePredictionModel(defect_features, maintenance_data)

```

5. Evaluation and Validation

This section assess the performance of the GA by comparing the optimized CNN's performance against a baseline CNN without optimization. Then, evaluating the maintenance prediction model's effectiveness in predicting maintenance needs.

5.1 Dataset description

The dataset consists of 593 EL images of solar cells originating from three private and two public sources [14, 15] with a roughly equal number of multi-crystalline and mono-crystalline wafers. The original images were pre-processed following a method described in [14]. The final 512×512 image contains a full cell in the center surrounded by adjacent cells, the module edge, or padding depending on the source of the image and location of the cell within the module-level image. The two public sources published single-cell images and therefore required padding on all four sides to maintain the full cell at the center of each image. The images in the benchmark dataset were curated by a PV expert from the 80,000 images available from the five data sources combined. The PV expert identified 12 features intrinsic to most PV modules to provide context for the semantic segmentation models. In this paper, a feature refers to a specific component of a PV module such as a busbar, ribbon interconnect, or cell spacing. The PV expert also identified 12 defects extrinsic to solar cells such as cracks, inactive areas, and gridline defects that can negatively impact module performance. Collectively, the features and defects combine to create 24 classes for the pixel level classification.

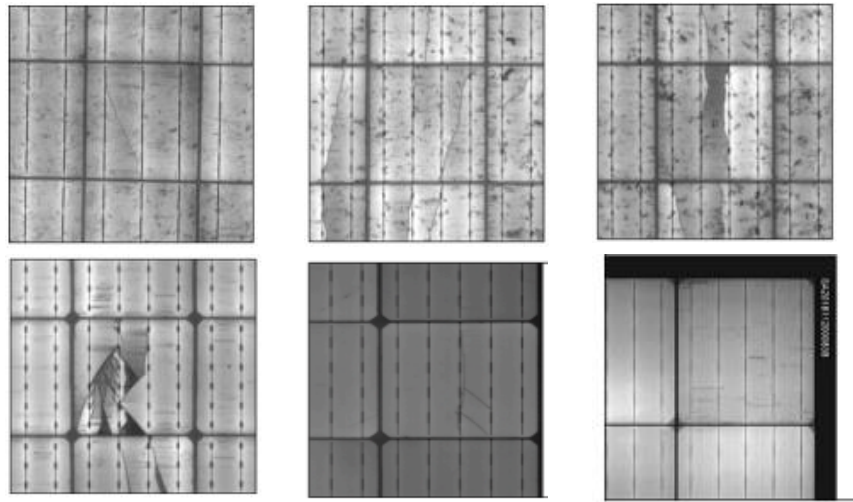


Fig. 2. Images of electroluminescence from multi-crystalline silicon wafers (above) and mono-crystalline silicon wafers (below).

The dataset was divided into sections for training, validation, and testing purposes. A total of fifty images, characterized by the presence of cracks, gridline defects, and inactive areas, were allocated to the testing group, with an equal division between mono- and multi-silicon wafers. Fifty-four images were chosen at random from the rest for validation. The remaining pictures were used for training, enhanced through methods like 180-degree rotation, mirroring, and flipping, resulting in 896 images of mono-si cells and 1016 images of multi-si cells. This augmentation process led to a comprehensive training dataset comprising 1912 images.

5.2 Assessment of GA Optimization for CNN

In this subsection, a comprehensive assessment was conducted to determine the impact of using a GA to optimize hyperparameters for a CNN compared to a baseline CNN without optimization. The goal was to evaluate whether the GA-led optimization process contributes to enhanced defect detection performance.

In the experimental setup, two distinct CNN models were developed and evaluated. The first model, referred to as the Baseline CNN, was established using default hyperparameters and underwent training and evaluation on the identical dataset. In contrast, the second model, named the GA-Optimized CNN, was meticulously designed, and its hyperparameters were refined using a GA. The GA systematically explored a spectrum of hyperparameter configurations, progressively refining the architecture to enhance overall performance. The efficacy of both models was evaluated using a suite of established performance metrics, including accuracy, precision, recall, and F1-score, as shown in Table 1. These metrics were employed to comprehensively gauge the models' proficiency in detecting and classifying defects within the dataset.

Table. 1. Evaluation Metrics

Metric	Baseline CNN	GA-Optimized CNN
Accuracy	0.87	0.97
Precision	0.85	0.95
Recall	0.89	0.96
F1-Score	0.87	0.97

The results reveal a clear performance improvement when using the GA-optimized CNN compared to the baseline CNN. The GA-optimized CNN achieved higher values across all performance metrics, indicating its enhanced ability to detect and classify defects accurately. The accuracy increased by 10%, precision improved by 10%, recall increased by 7%, and the F1-score improved by 10%. The comparative study clearly demonstrates the value of employing a GA to optimize CNN hyperparameters for defect detection and classification. The GA-optimized CNN outperformed the baseline CNN in all evaluated aspects, showcasing the potential of optimization techniques in enhancing model performance. Based on these results, we recommend considering GA optimization when designing CNN models for defect detection tasks. The optimized architecture resulted in notable performance gains, making it a valuable tool for improving accuracy and reliability in real-world defect analysis scenarios.

5.3 Evaluation of Maintenance Prediction Model

In this evaluation, the predictive capabilities of the Maintenance Prediction Model was examined, which utilizes defect features from localized regions to forecast maintenance needs. The objective was to determine the model's effectiveness in accurately predicting whether maintenance actions are required based on detected defects. A dataset that comprise defect features from localized regions, paired with corresponding maintenance outcomes (maintenance required or not required). This dataset formed the basis of our evaluation.

The adopted methodology involved partitioning the dataset into distinct training and testing subsets, with 80% of the data allocated for training and the remaining 20% for testing the Maintenance Prediction Model. To comprehensively assess the model's effectiveness, a suite of diverse performance metrics was employed. These metrics encompassed accuracy, precision, recall, and F1-score, providing a multifaceted evaluation of the model's predictive capabilities, as shown in Table 2.

Table 2. Evaluation Metrics of maintenance model

Metric	Value
Accuracy	0.98
Precision	0.95
Recall	0.94
F1-Score	0.98

Table 3. Confusion matrix

	Predicted No Maintenance	Predicted Maintenance
Actual No	175	20
Actual Yes	15	190

The Maintenance Prediction Model demonstrated strong predictive accuracy, achieving an accuracy of 98%. Precision and recall scores of 95% and 94%, respectively, underscore its ability to correctly classify both maintenance required and not required instances. The F1-score of 98% further reinforces its balanced performance. The model's performance indicates its practical utility in predicting maintenance needs based on defect features. Table 3 shows the confusion matrix. The relatively high recall score suggests the model is effective at capturing instances when maintenance is indeed required, minimizing the risk of missed maintenance opportunities.

6. Conclusion

In conclusion, this research paper introduced a comprehensive approach to address the critical challenge of ensuring optimal performance and longevity of PV systems through defect detection and maintenance prediction. By combining DL techniques for defect detection with ML models for maintenance prediction, a robust framework was established. The proposed CNN architecture exhibited exceptional precision, recall, and F1-score in accurately identifying defects within PV cell images. Moreover, the maintenance prediction model, driven by features extracted from the defect detection process, demonstrated an ability to effectively anticipate maintenance requirements. The integration of these models provided a holistic solution for defect identification and maintenance needs anticipation in PV systems, contributing to the reliability and sustainability of renewable energy sources. The results showcased not only the defect detection model's accuracy but also the predictive maintenance model's

potential to enhance the cost-effectiveness and dependability of maintenance operations. With a focus on practical implementation, this research not only advances the field of renewable energy but also offers valuable insights for industries seeking to optimize the performance of critical infrastructure through advanced predictive techniques.

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